UC San Diego

JACOBS SCHOOL OF ENGINEERING

Corporate Affiliates Program

AGENDA – CAP Executive Board Meeting – June 5, 2019 – 5:00-7:30 PM

5:00 – 6:00 Networking Hour – Engineering Student Projects

Haptic Interfaces Engineers for Exploration (E4E) NanoEngineering Technology Society (NETS)

Artificial Muscle Actuators Human-Powered Submarine

6:00 – 6:15 CAP Chairman – Nik Devereaux, Viasat

- New CAP Partners: Aira, D&K Engineering. GKN Aerospace, Hewlett-Packard, ServiceNow, ViaTouch Interactive Media
- Haptic Interfaces Presentation

Andrea Frank, 2 nd year Ph.D Student,	Aamodh Suresh, 3 rd year Ph.D Student,
Computer Science & Engineering	Mechanical & Aerospace Engineering

6:15 – 6:45 Dean's Report – Albert P. Pisano

- Rising Rankings and Scaling Education
- Advancing Research Collaborations
- Franklin Antonio Hall Update
- Systems Engineering & Co-op Status
- Strategic Plan 2020
- Engineering All Four Years (E4) Initiative Progress Professor Steven Swanson, Computer Science & Engineering
- 6:45 7:05 Faculty Presentation Michael Yip, Asst. Professor, Electrical & Computer Engineering Machine Learning Applications for Robot Control and Planning
- 7:05 7:20 Breakout Session Strategic Plan 2020

Table Discussion and Report Out

7:20 – 7:30 CAP Business – William W. Dyer, Director, Corporate Affiliates Program

- CAP Talent Programs Updates
- Research Expo Results
- MAE Senior Project Showcase
- Masters of Advanced Studies (MAS) Enrollment
- Spirit of Solar CAP Executive Cruise Save-the-Date
- Upcoming Events

Dates to Remember

MAE Senior Project Day
Deadline: Fall 2019 MAS Enrollment
CAP Executive Spirit of Solar Cruise
New Faculty Welcome
Shu Chien Lifetime Achievement Celebration
Sustainable Power & Energy Center (SPEC) Research Summit
Fall CAP Executive Board Meeting
Center for Wearable Sensors (CWS) Research Summit

<u>Jacobs School CAP Mission</u>: Drive the corporate affiliate strategy and build productive, substantive relationships between companies, faculty and students to achieve goals in research, recruitment and education in the interest of enhancing the reputation of the Jacobs School.

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JACOBS SCHOOL OF ENGINEERING Corporate Affiliates Program

2020 Strategic Plan – Discussion Questions

What are the bold, relevant breakout moves to enable the Jacobs School to accelerate our march to cachet?

- What are the important grand challenges that the Jacobs School is uniquely positioned to address?
- What is the role of systems engineering and data analytics in the modern engineering curricula?
- How can we innovate on industry-academia partnerships for the benefit of society?
- How can we rebrand Engineering as the intellectual hub for addressing complex societal problems that can no longer be resolved by deterministic models in siloed disciplines?
- How can we attract the best talent that represents changing demographics and culture?

Notes:

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JACOBS SCHOOL OF ENGINEERING Corporate Affiliates Program

Welcome CAP Executive Board June 5, 2019



CAP Chairman and Vice Chairman



Nik Devereaux

Director of Software Engineering Viasat



GB Singh Director of Engineering Solar Turbines

Welcome



JACOBS SCHOOL OF ENGINEERING Corporate Affiliates Program

Welcome New CAP Partners

















Wearable haptic navigational aid for the blind via ungrounded kinesthetic feedback

Andrea Frank and Aamodh Suresh



MAE 207: Haptic Interfaces Professor Tania Morimoto Department of Mechanical and Aerospace Engineering University of California, San Diego



I. Motivation



Source: CDC: Disability Impacts all of us, www.cdc.gov/dsiabilities

"The ability to move about and travel safely without assistance is one of the cornerstones of independence for people who are blind or visually impaired."

WH Jacobson. The art and science of teaching orientation and mobility to persons with visual impairments. 1993.

Traditional Solutions

- Personal guides
- Guide dogs
- White canes



Technical Solutions



GPS dependent



Specific infrastructure

but...

Inappropriate modes of communication



Monopolizes hands

Our solution

- Wearable haptic device
- Mimics a personal guide leading the VIP by the shoulder
- Mobile ungrounded kinesthetic feedback via simple eccentric mass arm



Our solution



GPS Independent



No Infrastructure



Intuitive Haptic Guidance



Hands-Free

II. Device Design

Working and Assembly of device



Working

- User feels a 'pull' from torque acting from weights.
- Stepper motor controls the direction of the 'pull' precisely.
- User can be guided through an obstacle environment.

Signaling

- Vibration: start/stop notification
- Torque angle: direction

Mechanical Design



Motor Connector

Torque arm extender



Weight holder



Tungsten Weights

- 3D printed parts.
- Modular design.
- Easy to manufacture and assemble.
- Variable torque design.

Electrical/ Electronics Design



- Stepper motors for precision and accuracy.
- Raspberry Pi 3 microcontroller.
- L298N motor drivers.
- Eccentric motor for vibro-tactile feedback.

III. Evaluation

$$Correct = \begin{cases} 1 & \text{if guess is correct} \\ -1 & \text{if guess is incorrect.} \end{cases}$$

$Confidence \in \{i \in \mathbb{Z} : i \in [0,5]\}$

Score = Correct × Confidence

User Study I: Effect of Torque



$$\tau = F \cdot r$$



User Study II: Effect of Angle

Angle: Between -90° and 90° in 15° intervals



User Study II: Effect of Angle

Angle: Between -90° and 90° in 15° intervals





User Study III: Effect of Transitions



Transitions:

- 1. Front to Left (FL)
- 2. Front to Right (FR)
- 3. Left to Front (LF)
- 4. Left to Right (LR)
- 5. Right to Front (RF)
- 6. Right to Left (RL)

User Study III: Effect of Transitions



Key Observations:

- People relied on transitions <u>more</u> than absolute position
- Duration of movement also played a part

IV. Contributions

- Novel, ungrounded indoor navigational aid for VIPs
- Average confidence score of 3.63 /5
- Transitions more informative than absolute state



V. Ongoing Work

AI and user feedback integration

- Camera for active perception
- Risk-Aware path planning ^[1]
 - Nobel prize winning Prospect Theory to model human perception of environment
 - Sampling based planner to generate optimal paths in perceived environment
 - Machine Learning to learn the human perception model
- Natural and intuitive human-like motion
- Incorporate preliminary user feedback to improve design

[1] *A. Suresh and S. Martinez* Planning under risk and uncertainty based on Prospect-theoretic models , Arxiv, April, 2019, arXiv:1904.02851.

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JACOBS SCHOOL OF ENGINEERING Mechanical and Aerospace Engineering



Tania Morimoto Assistant Professor Mechanical & Aerospace Engineering



Saurabh Jadhav Teacher's Assistant MAE207

Thank you! Questions?

DEAN'S BRIEF



Albert P. Pisano

Dean, Jacobs School of Engineering

Accelerating the March to Cachet



JACOBS SCHOOL OF ENGINEERING Corporate Affiliates Program

Rising Rankings!

(US News, March 2019)



- #6 Best Public Engineering School in US
- #11 Overall, up from #17 in 2016



Transforming Engineering Education....at Scale



- 250 Faculty, over 90 hires in last 5 years
- 2,749 Degrees Conferred in 2018
 - #2 in nation for bachelor's degrees awarded to women
 - #3 in nation for bachelor's degrees awarded overall
 - 2.3x growth in master's



Research & Innovation Leader



• \$188M Research Expenditures in FY2018 CAGR 6% Over 4 Years

• Approximately 1/3 of research is in partnership with industry

136 Jacobs School technologies licensed in the last 5 years



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Agile Research Centers and Institutes

- Nano-Immuno Engineering (NEW!)
- Contextual Robotics
- Wearable Sensors
- Wireless Communications
- Microbiome Innovation
- CHO Systems Biology
- Extreme Events Research
- Machine Integrated Computing and Security
- Visual Computing
- Engineered Natural Intelligence
- Sustainable Power and Energy
- Deep Decarbonization Initiative





Nano-Immuno Engineering Agile Center



- Bio-Inspired Materials and Technologies to Activate, Cloak from, or Program the Immune System.
- Innovations to treat and prevent Cancer, Heart Disease, Autoimmune or Infectious Disease.
- NanoEngineering, Bioengineering, Moores Cancer Center



Agile Research Centers Foster Industry Collaboration (70 Partners)



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Corporate Affiliates Program

Franklin Antonio Hall



Industry-relevant research centers under one roof creates a powerful ecosystem to build the digital future



Corporate Affiliates Program
Research Vision for the Digital Future





Collaboratories for the Digital Future

Machine-Integrated Computing and Security Institute for the Global Entrepreneur Halıcıoğlu Data Science Institute

Wearable Sensors

High Energy Density Science



Nanolmmuno Engineering | IEM

Precision Genomics | Salk

Contextual Robotics Institute

Sustainable Power and Energy



Innovation Ecosystem: Precision Medicine

Machine-Integrated Computing and Security Institute for the Global Entrepreneur

Halıcıoğlu Data Science Institute

Wearable Sensors

High Energy Density Science



Nanolmmuno Engineering | IEM

Precision Genomics | Salk

Contextual Robotics Institute

Sustainable Power and Energy



Innovation Ecosystem: Sustainable Cities

Machine-Integrated Computing and Security Institute for the Global Entrepreneur Halıcıoğlu Data Science Institute

Wearable Sensors

High Energy Density Science



Nanolmmuno Engineering | IEM

Precision Genomics | Salk

Contextual Robotics Institute

Sustainable Power and Energy



Innovation Ecosystem: Connected Health

Machine-Integrated Computing and Security

Institute for the Global Entrepreneur

Halıcıoğlu Data Science Institute

Wearable Sensors

High Energy Density Science

NanoImmuno Engineering | IEM

Precision Genomics | Salk

Contextual Robotics Institute

Sustainable Power and Energy



Franklin Antonio Hall Groundbreaking



Save the Date! 15 November 2019 @ 3 p.m.



Systems Engineering Education Initiative



You Said

- The proposed content is on point
- Go beyond ECE undergrads-consider a schoolwide BS/Co-op/MS program
- Make sure we add "stickiness" for corporate partners
- Include live design, test-driven design; models and visualization
- Make sure to focus on ethics and humans in the loop
- Machine Learning and AI will be key skills for the future

We Did

- All feedback part of the White Paper for Systems Engineering
- Reinforced our resolve to move forward with this initiative, incorporating components recommended by CAP
- Faculty recruitment underway
- Now expanding beyond ECE to Mechanical/Aerospace and Structural Engineering
- Goal of "Stickiness and Industry Connection" inspiring new ideas on Co-op as Innovation Accelerator



UC San Diego

Co-op Pilot Summer-Fall 2019

First in the UC System

Pilot to run July-December 2019

Over 450 student applicants

Thank you to our 13 participating CAP Partners





SCIENTIFIC



JACOBS SCHOOL OF ENGINEERING **Corporate Affiliates Program**

JACOBS SCHOOL STRATEGIC PLAN 2020



The Jacobs School Today





- One of the nation's largest engineering schools, providing leadership, talent and technology at scale
- Graduates recognized for core engineering knowledge that enables them to solve new problems
- Research powerhouse known for biotechnology & communications.....but we are much broader
- Working with industry is part of our DNA
- The engineering schools of the next decade will collaborate their way to greatness...

The Jacobs School in the Next decade



- Sustained Performance Reputation (10 Yrs)
- Sustained Reputation

Cache (20 Yrs)

- Drive towards relevance and cache
- No silver bullet--broad set of coordinated efforts
- Striving toward recognition (not ranking)
- Last Strategic Plan 2013
- Need unified voice of the faculty to ensure the right culture, attitude and inclusive Strategic Plan



2020 Strategic Plan – Discussion Questions





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Faculty Presentation



Steven Swanson

Professor, Computer Science & Engineering

Experience Engineering all Four Years (E4) Initiative



JACOBS SCHOOL OF ENGINEERING Corporate Affiliates Program

E4 Initiative: Hands-on Classes for All Engineering Students

- Founded ~2015
- Advantages of hands-on learning
 - Increased student engagement
 - Increased retention
 - Better-prepared for the real jobs
- Hands-on courses in all six engineering departments
 - Freshmen and sophomores Get them early!
 - Extending to the upper-division



The Envision Maker Studio

• Facilities

- 3500 sq ft of making space
- 2100 sq ft of classrooms
- Tools
 - 3D Printers
 - Laser cutter
 - Hand tools



- Staff director, assistant director, and faculty director
- "Envisionaries" student support staff



Jesse Dewald

Curt Schurgers

The Envision Maker Studio







Sign Ins

Classes in EnVision (per quarter)



ACADEMIC QUARTER

Total Enrollment in EnVision (per quarter)



What's Next for E4?

- Extending reach to upper division courses
- Coordinating with other hands-on initiatives across JSOE
 - Building a maker culture
 - Extending deeper into curricula
 - Avoiding replicated effort and easing access
- Evaluation of Teaching Effectiveness
 - What works best in hands-on education?
 - How can we track student success?



Faculty Presentation



Michael Yip

Assistant Professor, Electrical & Computer Engineering

Machine Learning Applications for Robot Control and Planning



JACOBS SCHOOL OF ENGINEERING Corporate Affiliates Program

Machine Learning Applications for Robot Control and Planning

Michael Yip, Ph.D. Assistant Professor, Electrical and Computer Engineering

ucsdarclab.com





<u>Acknowledgements</u>

Students Nikhil Das Florian Richter Ahmed Qureshi Dimitri Schrieber Winnie Kuang Naman Gupta Yuheng Zhi Mrinal Verghese Aaron Gunn

Other Collaborators

Ryan Orosco (Otolaryng.) Phil Weissbrod (Otolaryng.) Steve Hong (Otolaryng.) Alex Norbash (Radiology)





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and private donors

2016 Congressional U.S. Roadmap for Robotics



A Roadmap for US Robotics From Internet to Robotics 2016 Edition

Organized By

University of California San Diego Carnegie Mellon University Clemson University Cornell University Georgia Institute of Technology Northeastern University Northwestern University Oregon State University SRI Inc. Texas A&M University The University of Utah University of California Berkeley University of Nevada - Reno University of Southern California University of Tennessee Knoxville University of Washington University of Wisconsin Vanderbilt University Yale University Sponsored by:

National Science Foundation University of California San Diego Oregon State University Georgia Institute of Technology "The basic assumptions of most existing [robot] manipulation algorithms are not being satisfied in targeted application areas.

Truly autonomous manipulation will depend on the robot's ability to acquire adequate, task-relevant environmental models when they are not available."



Surgical Robotics Today



The Robot Process



The Robot Process



Levels of Autonomy





Saving lives across the US and the World

Robotic surgery to expands surgical access to high-quality, consistent, and immediate surgery.

The Golden Hour Rule



Key barrier to telerobotic surgery is **signal latency and degradation**





Without time delay







Clinician-specific Dynamic Scaling

Tailor motion scaling (shown to statistically reduce chance of errors) to specific clinician preferences or styles.





Each doctor is different



Augmented Reality Predictive Displays

Real-time visualization of expected instrument position over the delayed video stream.

Delayed Video










19% reduction in procedure time without negatively affecting human error

Learning Visuo-Haptic Feedback

Machine vision provides virtually generated haptic cues









Learning Controllers

Many complex systems have: Inaccurate or unknown system models Unknown environment dynamics

We can *learn* to control complex systems (BUT Wait! Not neural networks just yet!) Large Training Time Large amounts of data needed Lose sense of understanding





Online Model-free Control





Visual Adaptation

Ego-centric Navigation









Applications









What are some challenges?









Sampling: Configuration Space

Moving robot







Retrieving C-space Map

Naïve Approach: Run geometric collision detector on mesh bodies for all possible interactions: computationally costly!



Fastron: Classifier-based Collision Checker for Fast and Power-Efficient Collision Checking

Model-free classifier and active learning strategy to replace costly geometric collision checks



N. Das, N. Gupta, M. Yip, Conference on Robot Learning (CoRL), PMLR vol. 78, pp. 496-504, 2017. N. Das, M. Yip, U.S. Provisional Patent.

The kernel Perceptron Classifier







Active Learning Strategy

Exploitation:

Sample near boundary to observe dynamical changes

Exploration:

Sample in new areas Uniform or directed sampling



Responsive modeling in moving environments



Complexity vs. Computation



Number of Workspace Obstacles

Broad applications



Significant Mobile Planning Applications



Breakout Session – 2020 Strategic Plan

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CAP BUSINESS



William W. Dyer

Director, Corporate Affiliates Program, Jacobs School of Engineering

CAP Business



JACOBS SCHOOL OF ENGINEERING Corporate Affiliates Program



CAP Team update



Erica Kosa Interim Manager Talent Programs (TIP, Co-op, general recruitment) JacobsTIP@eng.ucsd.edu



Talent Programs 2019

Team Internship Program & Cooperative Education (Co-op)



Thank you to all 2019 TIP & Co-op Partners!



Corporate Affiliates Program

Start Early: 2019-2020 Recruitment

Schedule your Recruitment Strategy Meetings with the CAP Team!

- Students are accepting offers earlier and earlier
- Competition is fierce, especially in the Fall
- Utilize CAP to target the right students for your organization



Contact: **Paula Kreger** Services Manager, Corporate Affiliates Program <u>pkreger@eng.ucsd.edu</u> | 858-534-3148



Jia Zhuang, Best of Show **Research Expo 2019**

Biomimetic Nanoemulsions as a Blood Substitute for Oxygen Delivery in vivo

- NanoParticles that look and act like red blood cells
- Blood substitute with 3-month shelf life
- Does not activate immune system



leidos Lawrence Livermore National Laboratory

Qualcom

Many thanks to our CAP sponsors!

brain



Mechanical & Aerospce Engineering Senior Project Showcase

Stop by to chat with graduating seniors and see their capstone design hardware and posters

- Date: Wednesday, June 12, 11:30am 2:30pm
- Location: Price Center West Ballrooms
- 51 posters across Aerospace, Environmental, and Mecahnical Engineering



Cohu – Delta Design





Contact: **Professor Nate Delson** <u>ndelson@ucsd.edu</u> 858-534-0655 mae.ucsd.edu/design

Teradata

ATA Engineering



Master of Advanced Studies



Contact: **Phillip McMullen** Director, Executive Education <u>pmcmullen@eng.ucsd.edu</u> (858) 822-4536 Jacobsschool.ucsd.edu/mas



JACOBS SCHOOL OF ENGINEERING Corporate Affiliates Program MAS programs are interdisciplinary engineering degrees designed for working professionals with classes taught on Fridays and Saturdays every other week.

Architecture-based Enterprise Systems Engineering (AESE)

Engineering professionals with 5+ years of relevant professional experience who are in a position to drive enterprise systems

Wireless Embedded Systems (WES)

Engineering professionals with a background in CS / EE who want to enhance their understanding of IoT, edge computing, and 5G (6G...)

Data Science and Engineering (DSE)

Engineering professionals with a background in CS / Math / Statistics with substantial experience in data analysis

Fall 2019 Enrollment Deadline: June 24, 2019

Spirit of Solar CAP Executive Cruise



Save the date! 30 September 2019, 5-7:30pm



JACOBS SCHOOL OF ENGINEERING Corporate Affiliates Program

All Upcoming Opportunities

- June 12, 2019 MAE Senior Project Showcase
- June 24, 2019 Deadline: Fall 2019 MAS Enrollment
- September 30, 2019 CAP Executive Spirit of Solar Cruise
- October 2, 2019 New Faculty Welcome
- October 4, 2019 Shu Chien Lifetime Achievement Celebration
- October 4, 2019 Sustainable Power & Energy Center (SPEC) Research Summit

Center for Wearable Sensors (CWS) Research Summit

- October 10, 2019 Fall CAP Executive Board Meeting
- October 23, 2019
- UC San Diego

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<u>UC San Diego</u>

JACOBS SCHOOL OF ENGINEERING Corporate Affiliates Program

Thank You CAP Executive Board! Next Board Meeting: October 10, 2019